



Pitot tube based on mean square error algorithm for gas-liquid mixed phase flow gas flow measurement

28<sup>th</sup> June, 2019



# Content

**1 Background**

**2 Water film generate**

**3 Water film eigenvalue extraction  
and recognition**

**4 Water film remove**

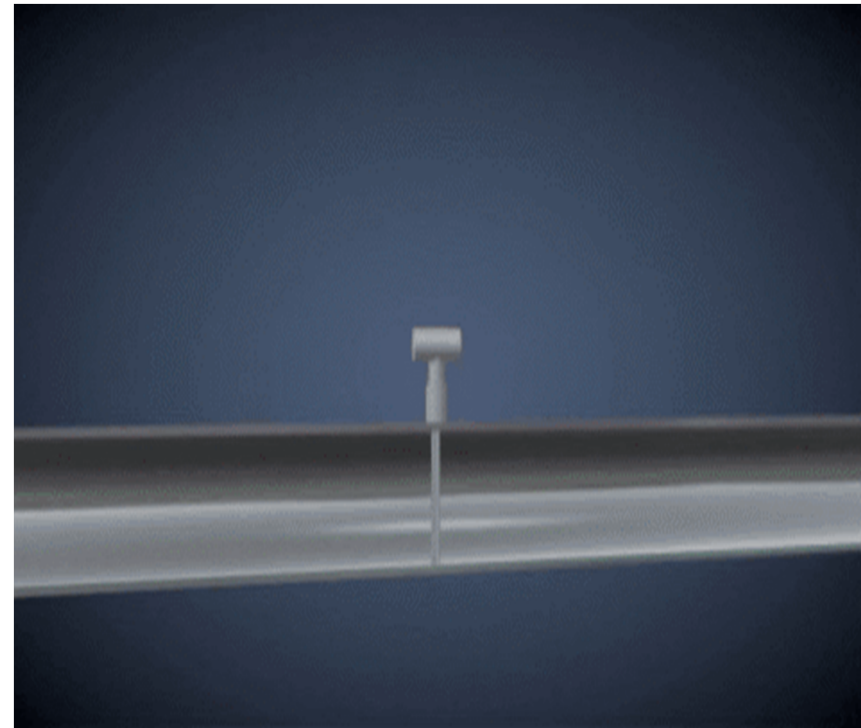


## Background

Determine the fluid flow by measures the differential pressure with the velocity in the oncoming flow and back flow of the sensor

formula:

$$v = k \sqrt{\frac{2 \Delta P}{\rho}}$$

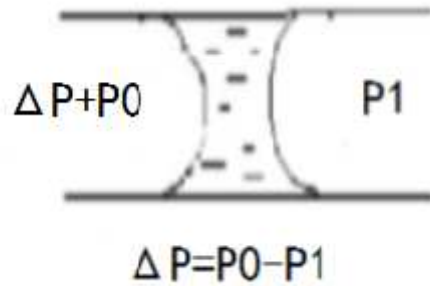




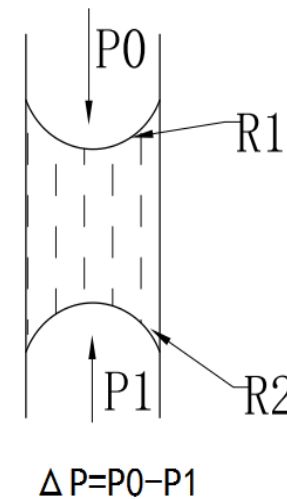
## Water film formation mechanism(1)

$$\Delta P = \begin{cases} 2\alpha(1/R_1 - 1/R_2) \\ 2\alpha(1/R_1 - 1/R_2) + \rho gh \end{cases}$$

horizontal installation  
vertical installation



Horizontal installation



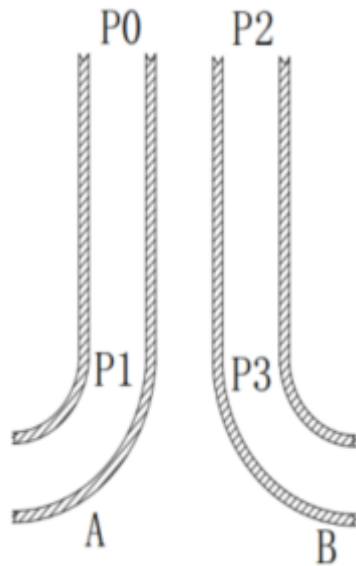
Vertical installation



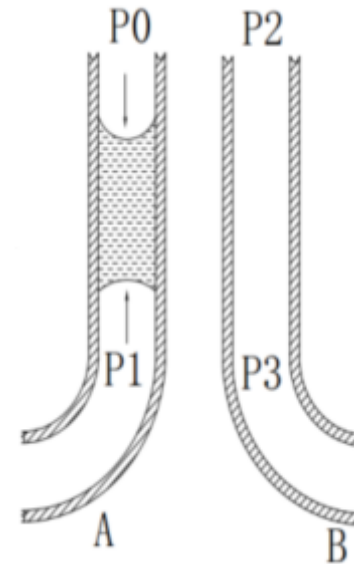
## Water film formation mechanism(2)



For example, operating temperature at 45°C, pressure is 0.3Mpa, and velocity is 5.34m/s in the pipeline. 10mm thick water film produced in the total pressure capillary and the radius of curvature of the two side of water film is 3mm and 5mm.



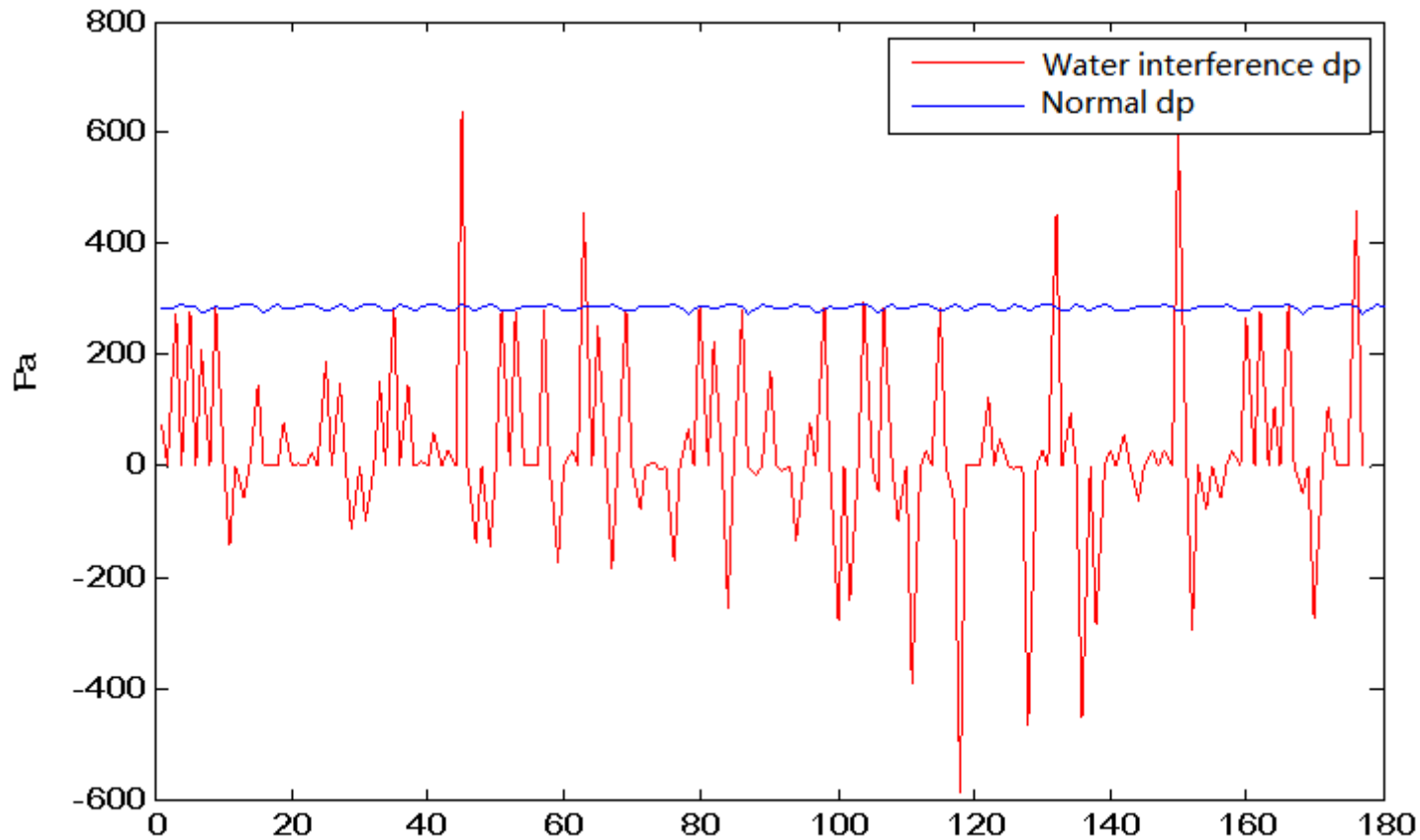
$$P = P_0 - P_2 = 150Pa$$



$$P = P_0 - P_2 = 30Pa$$

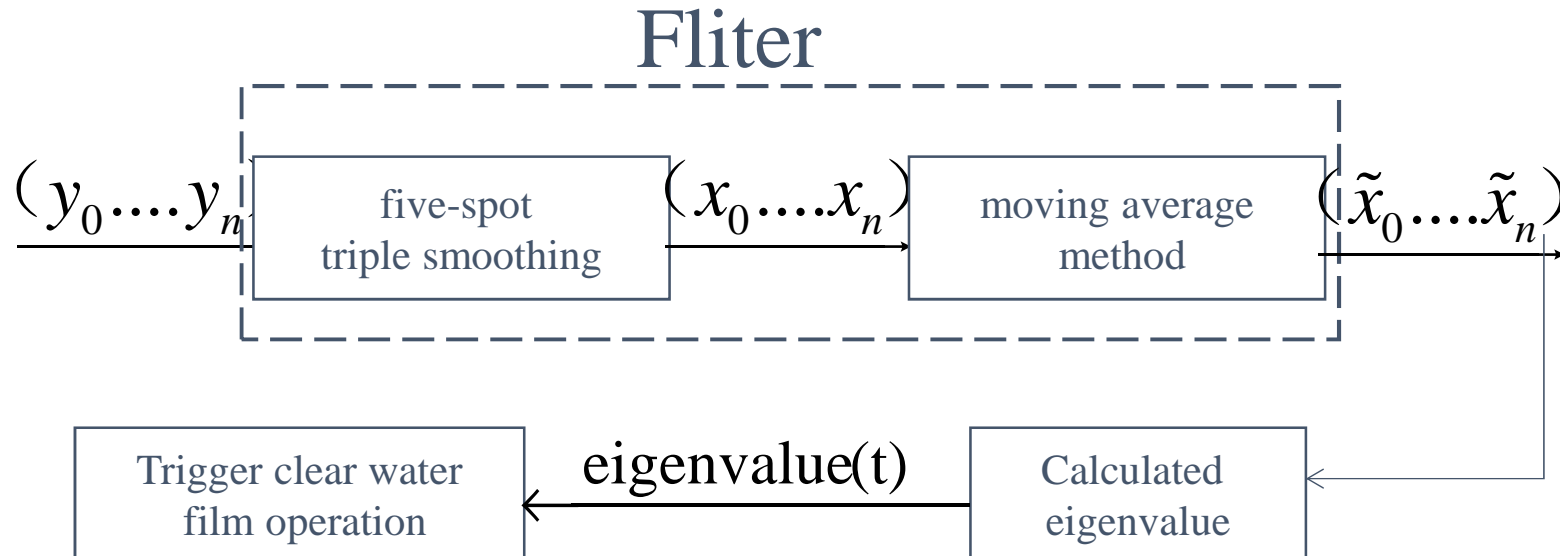


## Water film formation mechanism(3)





## Water film eigenvalue extraction and recognition



S1 : The dp sequence  $(y_1, y_2, \dots, y_n)$  acquired every second is filtered to obtain a sequence  $(x_1, x_2, \dots, x_n)$ ;

S2: calculating the eigenvalues of the sequence of  $(x_1, x_2, \dots, x_n)$  according to the mean square error formula;

S3: Judging the feature value  $t$  and the feature threshold  $T_0$  for water film recognition.

S4 : Trigger clear water film operation



## Water film eigenvalue extraction and recognition – Signal filtering(1)

### 1) five-spot triple smoothing

$$x_0 = 1/70(69y_0 + 4y_1 - 6y_2 + 4y_3 - y_4) \quad (1)$$

$$x_1 = 1/35(2y_0 + 27y_1 + 12y_2 - 8y_3 + 2y_4) \quad (2)$$

$$x_2 = 1/35(-3y_0 + 12y_1 + 17y_2 + 12y_3 - 3y_4) \quad (3)$$

$$x_3 = 1/35(2y_0 - 8y_1 + 12y_2 + 27y_3 + 2y_4) \quad (4)$$

$$x_4 = 1/70(-y_0 + 4y_1 - 6y_2 + 4y_3 + 69y_4) \quad (5)$$





# Water film eigenvalue extraction and recognition

## -Signal filtering(2)

2) moving average method

$$\tilde{x}_0 = (x_0 + x_1 + \dots + x_{m-1}) / m$$

$$\tilde{x}_1 = (x_1 + x_2 + \dots + x_m) / m$$

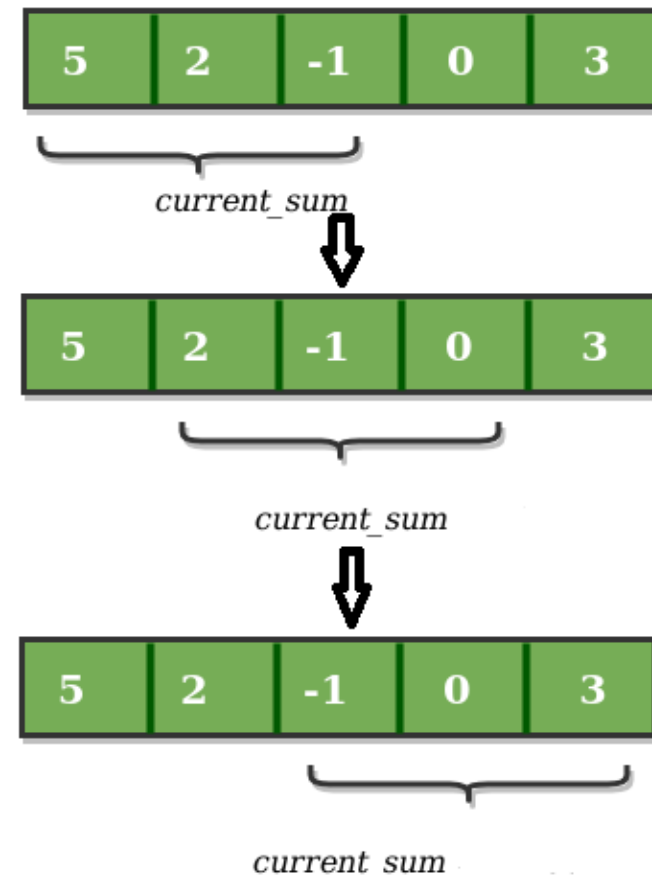
$$\tilde{x}_2 = (x_2 + x_3 + \dots + x_{m+1}) / m$$

$$\tilde{x}_n = (x_n + x_{n+1} + \dots + x_{n+m-1}) / m$$

In this :

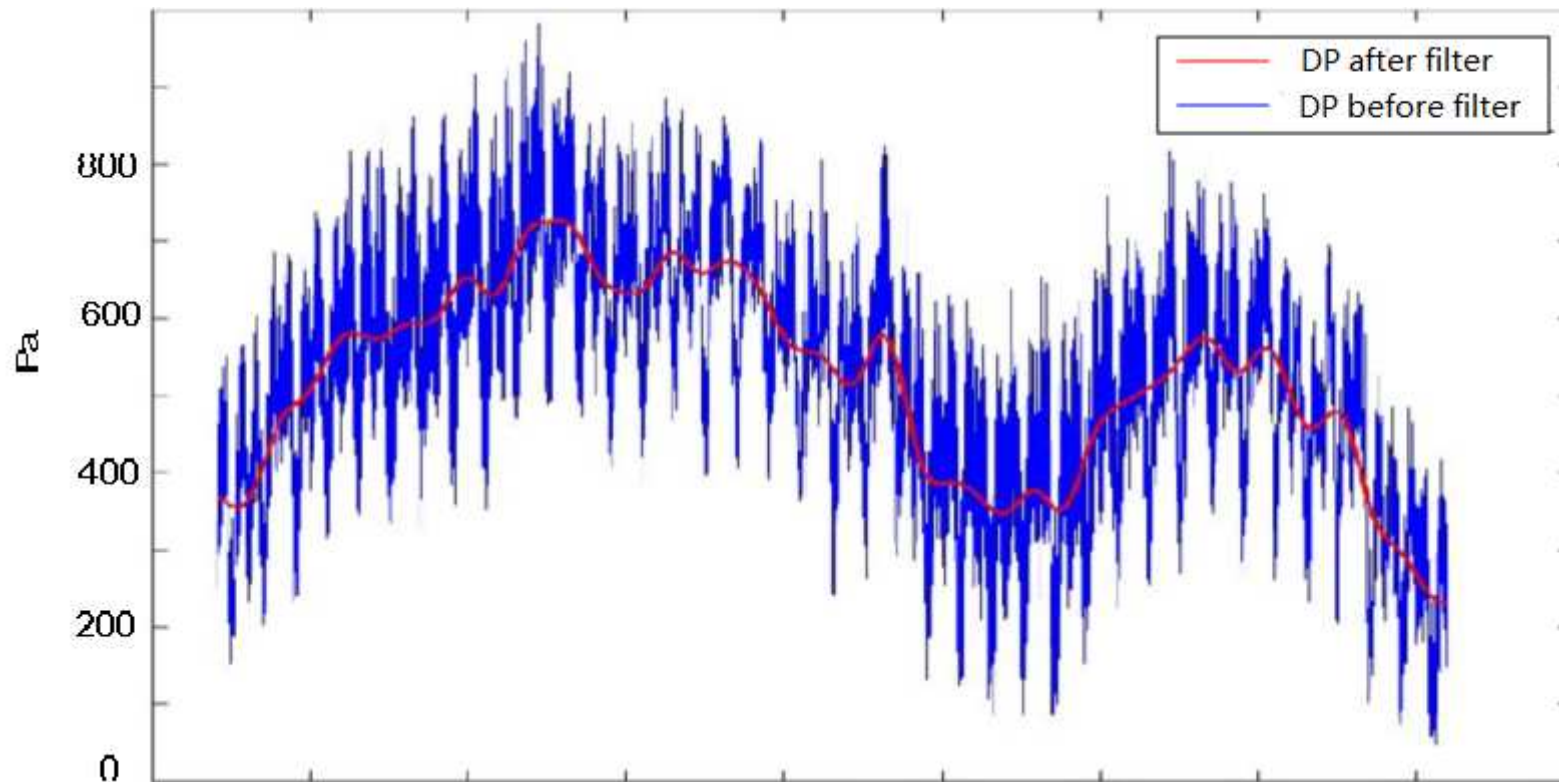
m: moving average number of sequences

$\tilde{x}_n$ : filter value of moving average of the point  $n$





## Water film eigenvalue extraction and recognition-filtering effect





## Water film eigenvalue extraction and recognition

Formula for eigenvalues :

$$\bar{x} = \frac{1}{N} \sum_{i=1}^N \tilde{x}_i \quad (1)$$

$$t = \sqrt{\frac{1}{N} \sum_{i=1}^N (\tilde{x}_i - \bar{x})^2} \quad (2)$$

$$\text{moist} = \begin{cases} N & t < T_0 \\ Y & t \geq T_0 \end{cases} \quad (3)$$

In the formula :

t: eigenvalue

$\bar{x}$ : DP sequence average

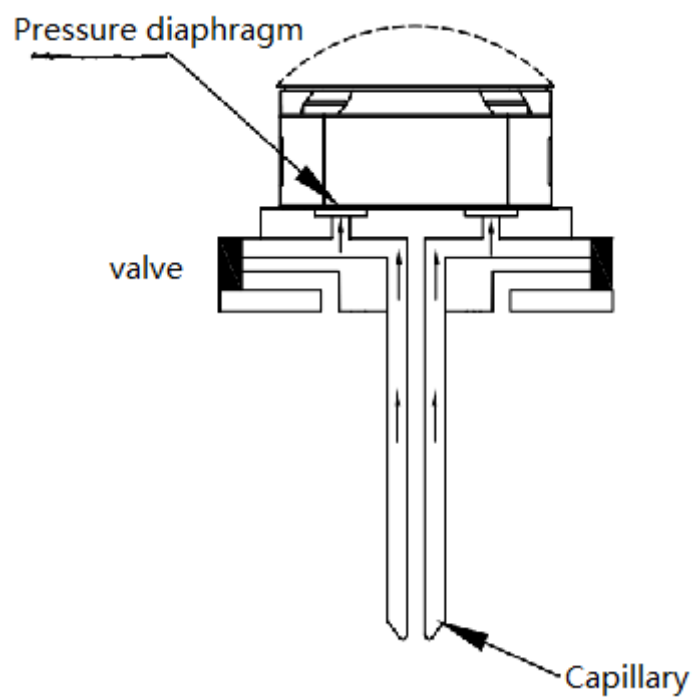
N: Number of dp sequences

$\tilde{x}_i$ : point data

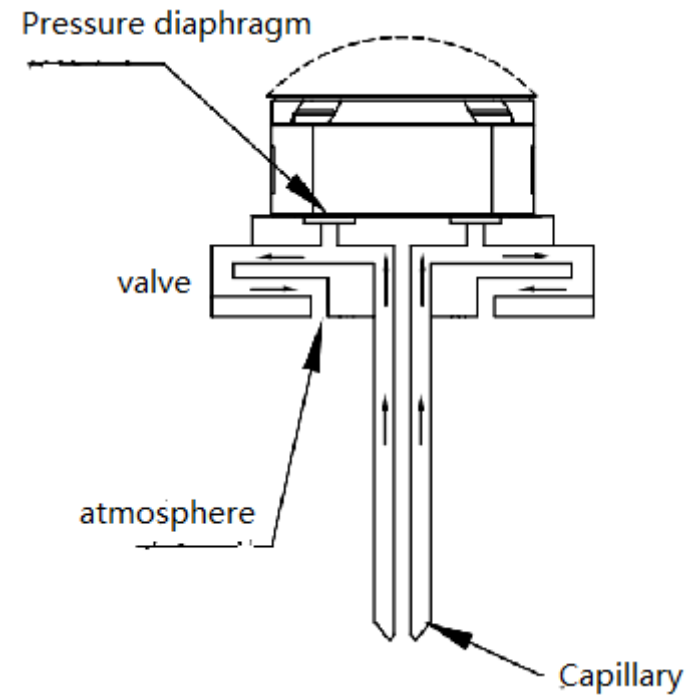
$T_0$ : eigenvalue threshold



## Water film remove



Normal status



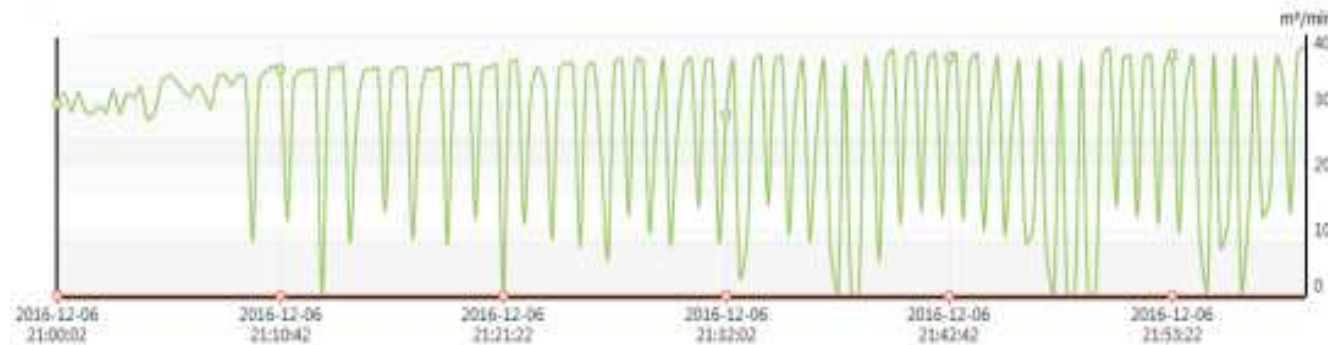
Water film eliminated



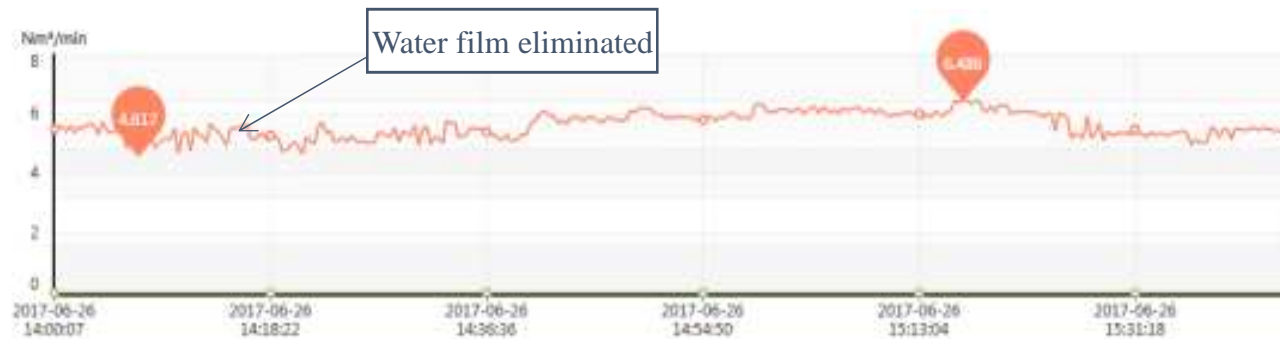


## Experimental result

Under water influence other type pitot tube flowmeter flow measuring curve :



Under water influence Comate pitot tube flowmeter flow measuring curve :





## Product

### Excellent in:

- ◆ 2.0% RD high accuracy
- ◆ Capable of working where there is vibration
- ◆ Supports online pressure installation
- ◆ High sensitivity
- ◆ Measure range: 1~30m/s (volume)



**Thank You for your attention!**  
**Any question?**

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Smart sensor

**COMATE**